Graphs and Graph Traversals

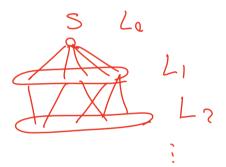
- a. Introduction to Graphs
- b. Graph Traversals: DFS
- c. Topological Ordering
- d. Breadth-First Search

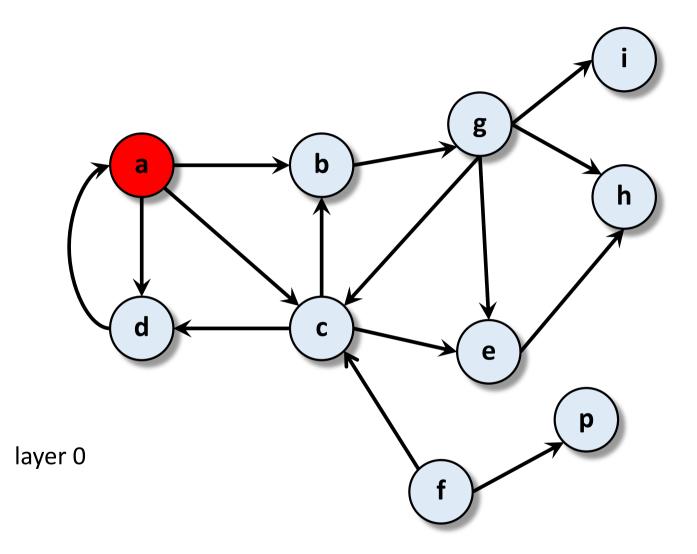
Exploring a Graph

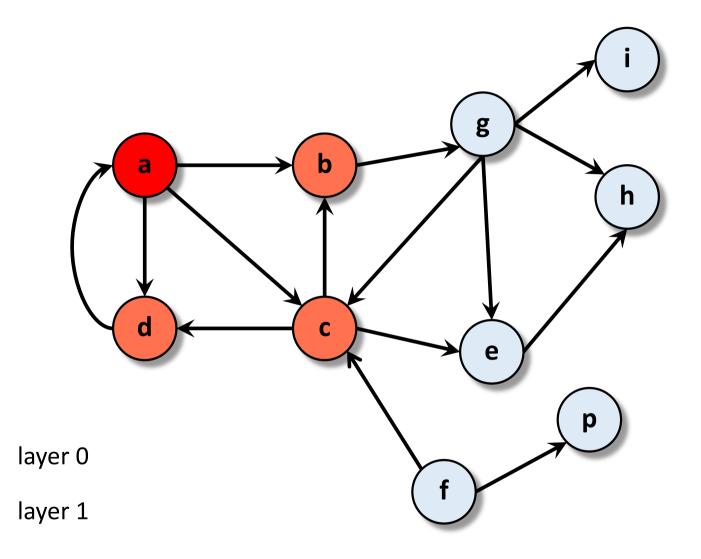
- **Problem:** Is there a path from *s* to *t*?
- Idea: Explore all nodes reachable from *s*.
- Two different search techniques:
 - Depth-First Search: follow a path until you get stuck, then go back
 - Breadth-First Search: explore nearby nodes before moving on to farther away nodes

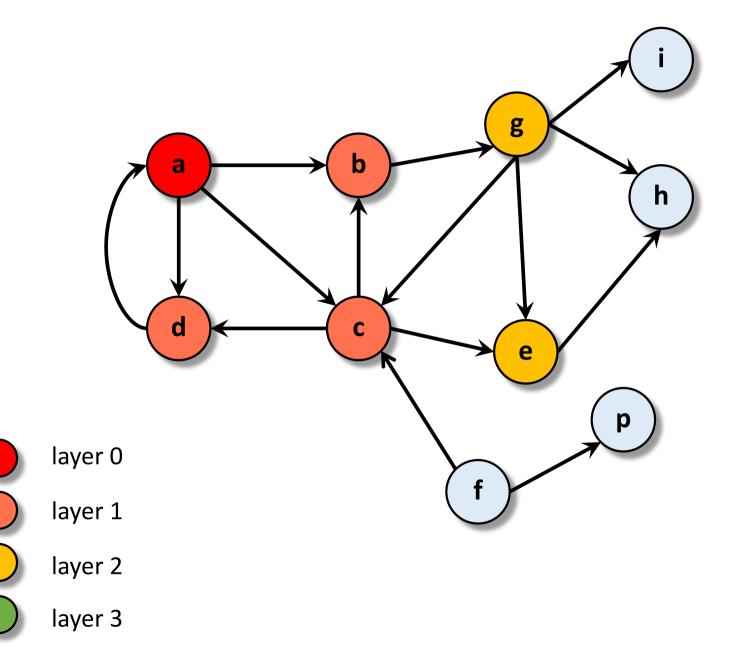
Breadth-First Search (BFS)

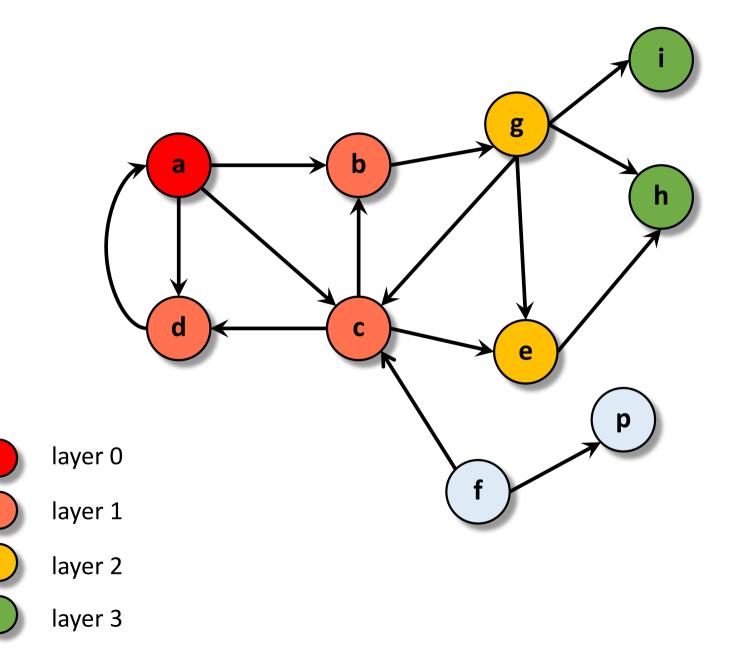
- Informal Description: start at *s*, find neighbors of *s*, find neighbors of neighbors of *s*, and so on...
- BFS Tree:
 - $L_0 = \{s\}$
 - $L_1 =$ all neighbors of L_0
 - $L_2 = \text{all neighbors of } L_1 \text{ that are not in } L_0, L_1$
 - $L_3 = all neighbors of L_2$ that are not in L_0, L_1, L_2
 - ...
 - L_d = all neighbors of L_{d-1} that are not in L_0 , ..., L_{d-1}
 - Stop when L_{d+1} is empty





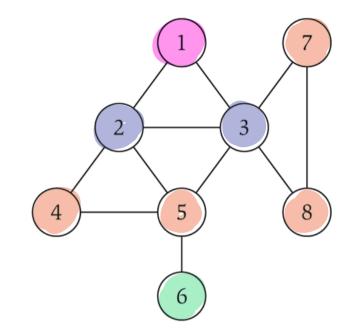






Ask the Audience

• BFS this graph from s = 1



Breadth-First Search (BFS)

- **Definition:** the distance between *s*, *t* is the number of edges on the shortest path from *s* to *t*
- Thm: BFS finds distances from s to other nodes
 - L_i contains all nodes at distance i from s
 - Nodes not in any layer are not reachable from s

Proof dy induction on 2. Base case 2=0. Assumightant Li-1 includes all rendres & distance it to 5, all & their neighbors not in Lo,..., Li-1, 1 must belong to Li and vice versa. 2 8 5 4

BFS Implementation (Adjacency List)

```
BFS(G = (V, E), s):
  discovered[v] = false \forall v, layer[v] = \infty \forall v
  Let i \leftarrow 0, L_0 = \{s\}
  layer[s] = 0
  discovered[s] = true
  while (L_i \text{ is not empty}):
     Initialize new layer L<sub>i+1</sub>
    For (u \text{ in } L_i):
       For ((u,v) \text{ in } E):
         If (discovered[v] = false):
            discovered[v] = true,
            layer[v] = i+1
            parent[v] = u
            Add v to L_{i+1}
    i = i + 1
```

Graphs and Graph Traversals

- a. Introduction to Graphs
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- d. Breadth-First Search
- e. Bipartite Graphs and Graph Traversals Recap

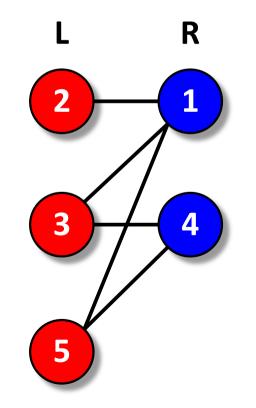
Practice Problem: 2-Coloring

- Problem: Tug-of-War
 - Need to form two teams **R**, **B**
 - Some students just don't get along
- Input: Undirected graph G = (V, E)
 - $(u, v) \in E$ means u, v will not be on the same team
- Output: Split V into two sets R, B so that no pair in either set is connected by an edge



2-Coloring (Bipartiteness)

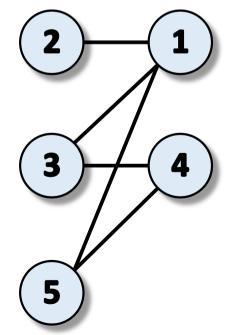
- Equivalent Problem: Is the graph G bipartite?
 - G is bipartite if V can be split into two sets L and R such that all edges $(u, v) \in E$ go between L and R



Designing the Algorithm

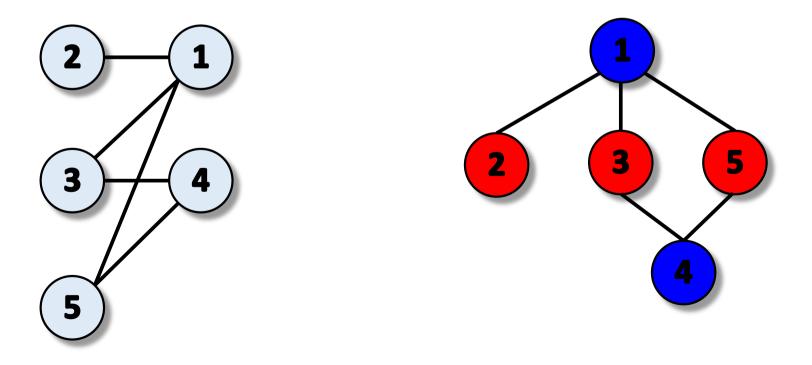
Idea for the algorithm:

- BFS the graph, coloring nodes as you find them
- Color nodes in layer *i* blue if *i* even, red if *i* odd
- Go over all edges and check if their endpoints have received different colors.



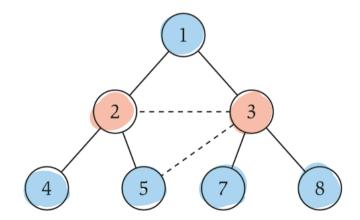
BFS 2-Coloring Success Implies Bipartite

- **Claim:** If our algorithm succeeds, the graph is bipartite (i.e., can be 2-colored)
- **Proof:** Immediate since our algorithm checks validity of the coloring at the end.



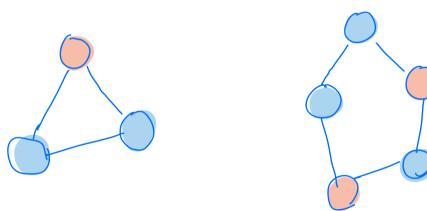
BFS 2-Coloring Failure Implies Not Bipartite

- **Claim:** If our algorithm did not succeed, the graph is not bipartite (i.e., cannot be 2-colored)
- **Question:** Suppose you have not 2-colored the graph successfully, maybe someone else can do it?





• Key Fact: If G contains a cycle of odd length, then G is not 2-colorable/bipartite



BFS 2-Coloring Failure Implies Not Bipartite

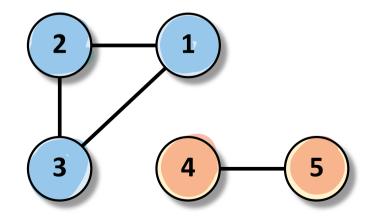
- **Claim:** If BFS did not 2-color the graph, the graph is not bipartite (i.e., cannot be 2-colored)
- Proof: If BFS fails, then G contains an odd cycle

Since BFS fails, Here is an edge (4,29) such that u and 22 are assigned He same calars. First wand a must be in the same layer, as attenuise whichever discovered first would adel the other to the next layer. Let u be a common ancestor f, u and re furthest from the source. We claim that (P(w, w), (u, v), P(v, w)) W Is an odd cycle. This is because, P(w, u) and P(v,w) have the same lengths.

Graphs and Graph Traversals

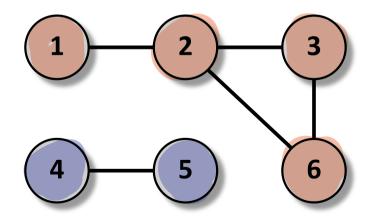
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- f. Connected Components

- An undirected graph is connected if for every two vertices $u, v \in V$, there is a path from u to v
- connected component: a maximal subset of vertices which are all connected in G



• Algorithm:

- Pick a node v
- Use DFS or BFS to find all nodes reachable from v
- Labels those as one connected component
- Repeat until all nodes are in some component



```
CC (G) :
 // Initialize an empty array and a counter
 let comp[1:n] = \bot, c = 1
 // Iterate through nodes
  for (u = 1, ..., n):
   // Ignore this node if it already has a comp.
   // Otherwise, explore it using DFS
   if (comp[u] = \bot):
     run DFS(G,u)
     let comp[v] = c for every v found by DFS
     let c = c + 1
 output comp[1:n]
```

Running Time

```
CC(G):
let comp[1:n] = \bot, c \leftarrow 1
for (u = 1, ..., n):
if (comp[u] = \bot):
run DFS(G, u) \leftarrow
let comp[v] = c for every v
found by DFS
let c = c + 1
output comp[1:n]
```

DFS takes O(n+m) time Vinitialization > m' is the # J. veachable edges from the source. Therefore, averall this falses O(n+m) times

when run on all cannoch

componuts.

- **Problem:** Given an undirected graph *G*, split it into connected components
- Algorithm: Can split a graph into connected components in time $\Theta(n + m)$ using DFS
- Punchline: Usually assume graphs are connected
 - Implicitly assume that we have already broken the graph into CCs in $\Theta(n+m)$ time

Graph Traversals Recap

• Basic Graph Theory:

- Degrees, paths, cycles, trees
- Graph representations:
 - Adjacency list and adjacency matrix

• Depth-First Search:

- Discovery and finish times
- Tree, forward, back, and cross edges
- DFS from any node takes O(n + m) time
- DAGs:
 - No directed cycles, no back edges
 - Topological ordering in $\Theta(n+m)$ time

Graphs and Graph Traversals Recap

• Breadth-First Search:

- Explores from start node, splits nodes into layers
- Min-hop path from start to all other reachable nodes
- BFS from any node takes O(n + m) time
- Can be used to determine if undirected graph is bipartite

• Connected components:

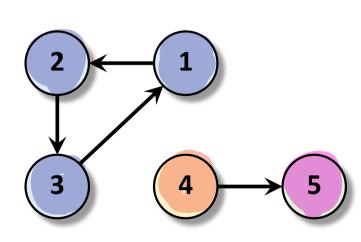
- Splits graph into its connected components
- Straightforward $\Theta(n+m)$ time application of DFS and BFS

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- f. Connected Components
- g. Strongly Connected Components

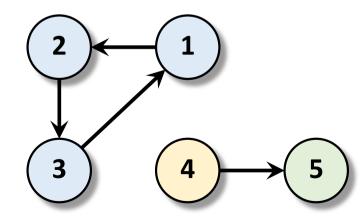
Strongly Connected Components

- **Definition:** In a directed graph, we say two vertices u and v are strongly connected if there is a path from v to u and a path from u to v.
- A strongly connected component is a maximal set of vertices all two of which are strongly connected.



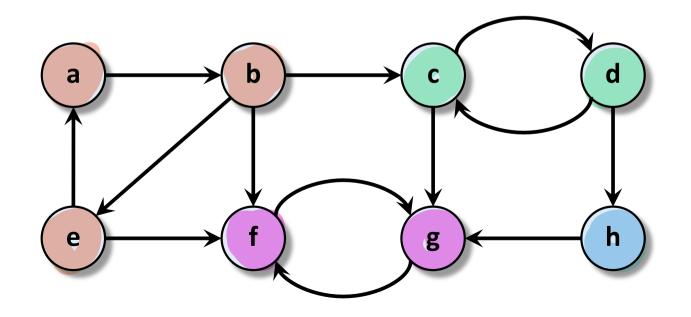
Strongly Connected Components

- **Problem:** Given a directed graph *G*, split it into strongly connected components
- Input: Directed graph G = (V, E)
- Output: A labeling of the vertices by their strongly connected component



Ask the Audience

• Find all the strongly connected components (SCCs) of this directed graph



Strongly Connected Components

- **Observation:** SCC(s) is all nodes $v \in V$ such that v is reachable from s and vice versa
 - Can find all nodes reachable from *s* using DFS
 - How do we find all nodes that *can reach s*?
 - DFS(*s*) in reverse of the graph!

SCCs by DFS

```
Runs in
SCC-Slow():
                                                            n(n+m) time
  G^{R} = G with all edges "reversed"
  // Initialize an array and counter
  comp[1:n] = \bot, c = 1
  for (u = 1, ..., n):
      S = set of nodes found by DFS(G,u) ? O(n+m) O(n+m) 
T = set of nodes found by DFS(G<sup>R</sup>,u) ? O(n+m) five 
five 
label S O T with
     // If u has not been explored
     if (comp[u] = \bot):
       label S \cap T with c
       c = c + 1
```

return comp